version	1.1.0
scope	Example. This code is provided as example code for a user to base their code on.
description	How to control the XTA from a python script
boards	Unless otherwise specified, this example runs on the SliceKIT Core Board, but can easily be run on any XMOS device by using a different XN file.

There are occasions when the inbuilt XTA command scripting mechanism does not offer the required level of power and/or flexibility. For example, you may wish to pass arguments to a script, use the return value of one command as input to another or make use of conditional/looping constructs. With this in mind, the XTA provides an interface which allows the tool to be controlled from Python scripts.

For example, compile the following code:

```
#include <stdlib.h>
#include <xs1.h>
port p1 = XS1_PORT_1A;
port p2 = XS1_PORT_1B;
int main() {
  int x;
  #pragma xta endpoint "input"
  p1 :> x;
  // Checks for errors..
  if (x == 1) {
    #pragma xta label "error_case"
    exit(1);
  }
  // do some computation here..
  #pragma xta endpoint "output"
  p2 <: 0;
  return 0;
}
```

-XMOS

Publication Date: 2013/7/23 XMOS © 2013, All Rights Reserved As an example, assume that you want to time from the input to the output, set a requirement and exclusion, and this this must be done from a Python script. To achieve this, place the following lines in a file, e.g. script.py:

```
import java
try:
   xta.load("a.xe");
except java.lang.Exception, e:
   print e.getMessage()
try:
   xta.addExclusion("error_case")
   ids = xta.analyzeEndpoints("input", "output")
   for id in ids:
      print xta.getRouteDescription(id) + ":",
      print xta.getWorstCase(id, "ns"),
except java.lang.Exception, e:
   print e.getMessage()
```

The above script can then be run using the XTA source command:

xta source script.py -exit

Note: See the XMOS-Timing-Analyzer-Manual for further information on available interface methods.



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